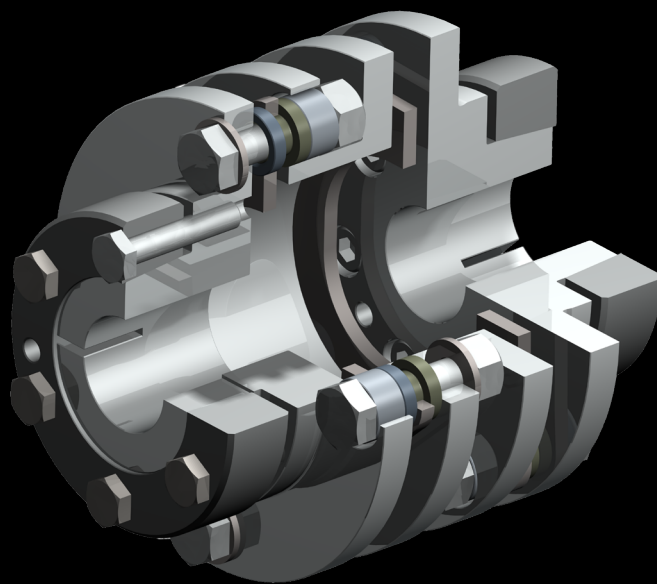


**Mönninghoff**

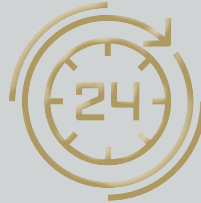
# **ServoFlex Type 338**



## ServoFlex - Type 338

### Characteristics and features

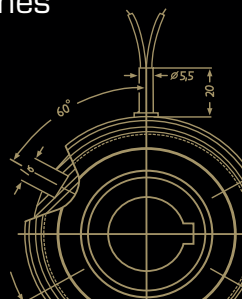
- particularly lightly through the use of aluminum
- torque transmission is free of backlash and torsionally stiff
- wear-free and maintenance-free
- high misalignment values
- high strength and bending elasticity stainless steel disc pack
- membrane shape is optimized with finite element design methods
- small resultant restoring forces
- transmitted torque up to 500 Nm, depending on the angular misalignment
- higher torque possible for special designs
- recommended temperature range: -35 °C to 150 °C  
use outside of this spectrum on request
- single and double joint designs
- spacer made of CFK/GFK or spring steel on request
- spacer also possible in use case-related lengths
- on request with ATEX-approval  $\text{Ex}$  II 2GD c IIC X / I M2 c (hub design 1 or 2)  
or  $\text{Ex}$  II 3GD c IIC X (hub design 4)



Mönninghoff power transmission represents an infinite variant diversity that is applied by all areas of modern mechanical engineering.

Our technologies are mostly designed to operate under extreme conditions. We offer high precision products for medical robotics, fail-proof security for aerospace technology or synchronization solutions for the packaging or printing industry.

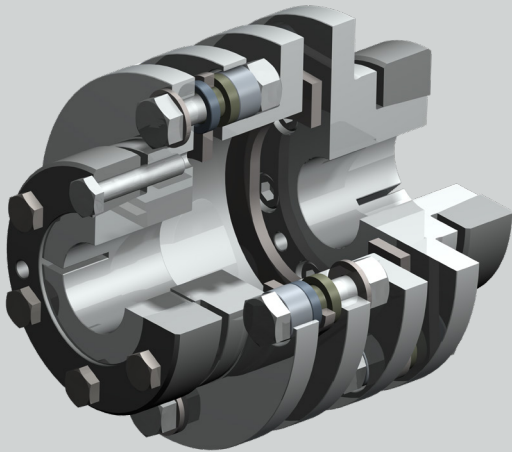
We thus address customers who have the highest standards for their own machines or systems. To them, we can offer highly complex, application-specific solutions.



## ServoFlex - Type 338

### Match code

Mönninghoff shaft couplings are indicated by the following match code:



#### 338 . A . B . C

**A** coupling size

**B** design

**C** options of mounting and integrating

other individual characteristics:

- bore size with keyways

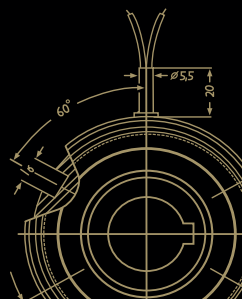
According to these characteristics, we design individual solutions concerning transmitted torque, engaging behavior or rotation speed.

Our engineers can assist with finding an application-specific coupling at any time. Together, we can develop individual and innovative solutions for extreme operating conditions.

### Ordering example

Mönninghoff ServoFlex - Coupling  
Type 338.38.2.4

Bore size d	26 mm H7, keyway acc. to DIN 6885/1
Bore size d <sub>1</sub>	26 mm H7, keyway acc. to DIN 6885/1



## ServoFlex - Type 338

### Coupling size

When dimensioning a Mönninghoff ServoFlex coupling, several technical preconditions should be considered:

- Membrane coupling transmit torque without virtually any dampening. Therefore the size must be determined so that a possible peak torque - caused by drive or load - does not exceed the specified nominal torque  $T_{KN}$ . We recommend that the torque which have been determined theoretically are corrected with the appropriate safety or operating factor.

$$T_{KN} > T \cdot K_B \text{ oder } T_{KN} > T \cdot K_S$$

- As misalignment reduces the transmitted torque of the coupling, the values specified for  $T_{KN}$  in the table must be taken into consideration depending on the angle of displacement. In the case of alternating operation and the demand for backlash free torque transmission, the alternating torque may not be exceeded.

$$T_{KW} > T \cdot K_B \text{ oder } T_{KW} > T \cdot K_S$$

- In the case of servo-drives and inverter controlled drives, possible maximum torque must be taken into consideration due to the interaction between motor and controller.

$$T_{Motor} = \frac{9550 \cdot P_{Motor}}{n}$$

- If clamping hubs or clamping elements are used, the max. torque which can be transmitted by the clamping connection must be taken into consideration.

$T$  = torque

$T_{KN}$  = nominal torque

$T_{KW}$  = alternating torque

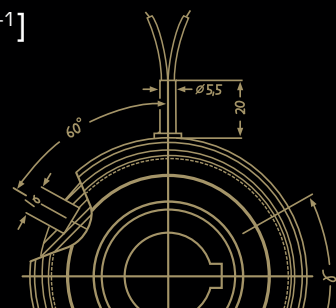
$K_B$  = operating factor

$K_S$  = shock factor

$T_{Motor}$  = torque of the motor

$P_{Motor}$  = power of the motor [kW]

$n$  = max. speed [ $\text{min}^{-1}$ ]



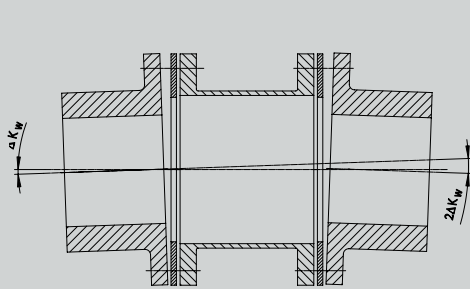
## ServoFlex - Type 338

### Coupling size - starting factor

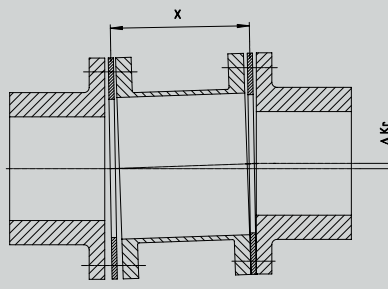
If the starting factor is bigger than 2 times of the coupling torque, or if there are more than 50 starts/stops per hour, please consult our engineers.

### Coupling size - angular misalignment factor

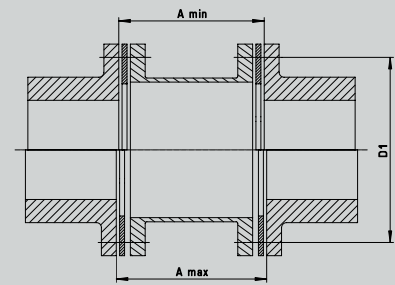
When calculating the angular misalignment factor, the radial and axial misalignment must also be taken into account.



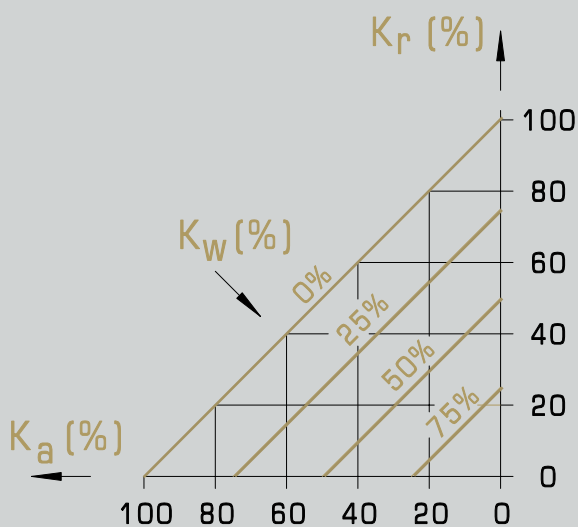
angle misalignment



radial misalignment



axial misalignment



$$\Delta K_{\text{total}} = \Delta K_a + \Delta K_r + \Delta K_w \leq 100\%$$

modification of  $\Delta K_a$  [mm] and  $\Delta K_r$  [mm] in  $\Delta K_{wa}$  [°] and  $\Delta K_{wr}$  [°]

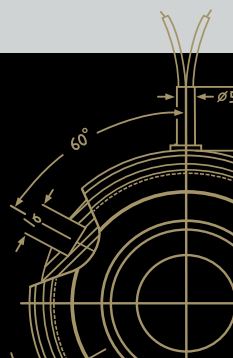
$$\Delta K_{wa} = \arcsin \frac{\Delta K_a}{0,75 \cdot D_1} [^\circ]$$

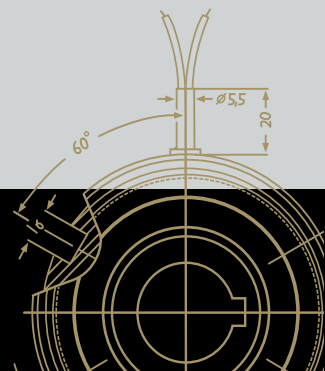
$$\Delta K_{wr} = \arcsin \frac{\Delta K_r}{x} [^\circ]$$

$$\Delta K_{wg} = \Delta K_w + \Delta K_{wa} + \Delta K_{wr} [^\circ]$$

X = distance of membrane  
K<sub>wg</sub> = total angular misalignment

K<sub>wa</sub> = angular misalignment axial  
K<sub>wr</sub> = angular misalignment radial

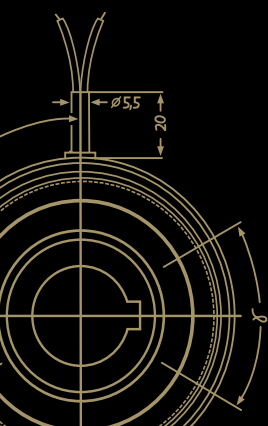




# ServoFlex - Type 338

## Technical data

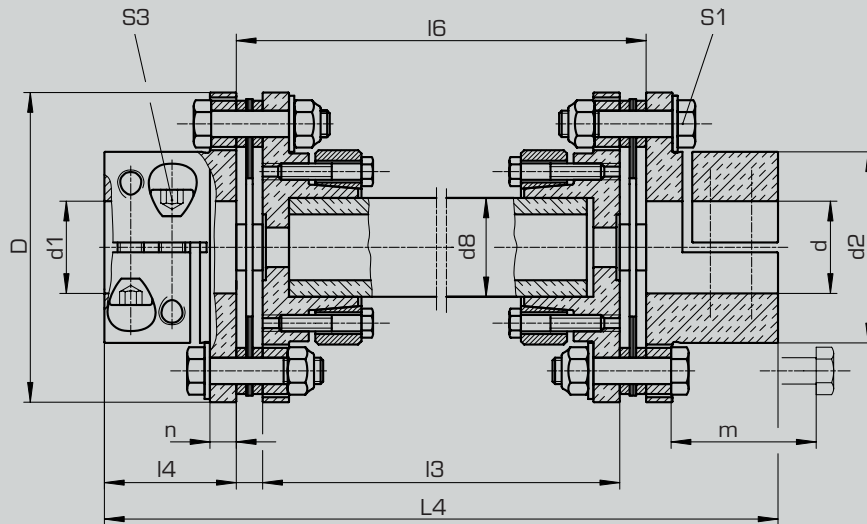
Size			20	25	35	38	42	50
torque at	0,50°	[Nm]	35	60	150	200	300	500
angular misalignment	$T_{KN}$ 0,75°		25	40	100	120	160	200
per membrane pack	1,00°		10	25	50	70	—	—
design 4._	$T_{KMax}$	[Nm]	25	45	55	120	135	250
alternating torque	$T_{Kw}$	[Nm]	18	40	55	120	135	250
max. misalignment	angular	type 1._	1	1	1	1	1	1
		type 2._, 4._	2	2	2	2	2	2
	axial	type 1._	0,6	0,8	1	1,2	1,4	1,6
		type 2._, 4._	1,2	1,6	2	2,4	2,8	3,2
	offset	type 2._	0,5	0,5	0,5	0,6	0,6	0,8
		type 4._	0,1	0,2	0,2	0,3	0,3	0,4
max. speed	n	[min <sup>-1</sup> ]	on request					
inertia	type 1._	I [10 <sup>-3</sup> kg m <sup>2</sup> ]	0,11	0,30	0,87	1,6	2,6	6,5
	type 2._		0,20	0,55	1,5	2,9	4,6	11,8
	type 4._		0,15	0,42	1,1	2,2	3,6	9,2
weight	type 1._	[kg]	0,13	0,26	0,43	0,6	0,9	1,5
	type 2._		0,21	0,47	0,72	0,96	1,4	2,4
	type 4._		0,17	0,4	0,51	0,8	1,2	2,1
torsional stiffness	type 1._	$C_t$ [10 <sup>6</sup> Nm/rad]	0,016	0,029	0,083	0,17	0,25	0,43
	type 2._, 4._	$C_k$ [10 <sup>2</sup> Nm/rad]	0,007	0,013	0,037	0,072	0,109	0,185
axial stiffness	type 1._	[Nm/mm]	43	45	60	122	160	197
	type 2._, 4._		21	22	30	61	80	98
screw S1	size	[Nm]	M5	M6	M6	M 8	M 8	M 10
	tightening torque		5,5	13	13	33	33	65
dimensions	D	[mm]	56	68	82	94	104	128
	d/d <sub>1</sub> min. H7		12	12	19	24	20	25
	d/d <sub>1</sub> max. H7		17	22	32	32	35	42
	d <sub>2</sub>		32	40	54	58	68	78
	d <sub>4</sub>		35	42	56	59	70	82
	d <sub>5</sub>		27	35	48	50	60	69
	d <sub>7</sub>		20	24	28	32	34	40
	L		45	56	66	68	80	91
	L <sub>1</sub>		56	70	80	88	102	116
	L <sub>2</sub>		74	88	98	106	118	140
	I		20	25	30	30	35	40
	I <sub>1</sub>		16	20	20	28	32	36
	I <sub>2</sub>		24	26	26	30	28	38
	I <sub>4</sub>		25	30	35	40	50	55
	S		5	6	6	8	10	11
	s		5	6	6	8	10	11
	s <sub>i</sub>		—	16	16	16	18	19
	x		50	62	72	76	90	102
	m type 1._, 2._	min.	27	31	35	44	44	57
	m type 4._	min.	20	24	26	35	35	44



## ServoFlex - Type 338

### Design .3 with variable spacer

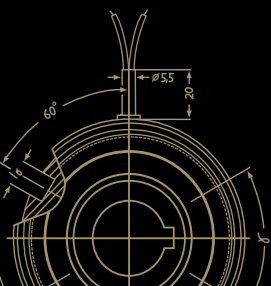
The double joint design has some additional properties of the spacer to consider.



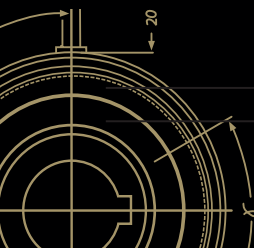
- length changes through temperature variations are possible
- spacer length  $l_3$  is limited to 1500 mm or 2000 mm due to the manufacturing process
- spacer material in CFK or GFK on request possible

### Technical data

Size			20	25	35	38	42	50
torque			see first table					
max speed	n	[min <sup>-1</sup> ]	on request					
inertia	by $l_3 = 1000$ mm	[10 <sup>-3</sup> kg m <sup>2</sup> ]	0,16	0,42	1,19	2,07	3,49	8,89
	per 100 mm		0,002	0,004	0,009	0,017	0,029	0,069
weight	by $l_3 = 1000$ mm	[kg]	0,53	0,93	1,71	2,26	3,07	4,7
	per 100 mm		0,03	0,04	0,09	0,11	0,13	0,17
torsional stiffness pipe	$C_a$	[10 <sup>6</sup> Nm/rad]	0,2 : l3	0,4 : l3	0,9 : l3	1,8 : l3	3,1 : l3	7,1 : l3
axial stiffness	$C_s$	[Nm/mm]	21	22	30	61	80	98
screw S1	size	[Nm]	M5	M6	M6	M8	M8	M10
	tightening torque		5,5	13	13	33	33	65
screw S3	size	[Nm]	M4	M5	M6	M8	M10	M10
	tightening torque		3,6	7	11	25	50	50
max. misalignment	angula	[°]	2	2	2	2	2	2
	axial	[mm]	1,2	1,6	2	2,4	2,8	3,2
	offset	[mm]	0,0175 (l3 + s)					
bore d, d1 H7	min.	[mm]	12	12	19	20	20	25
	max.		17	22	32	32	35	42
dimensions	D	[mm]	56	68	82	94	104	128
	d <sub>2</sub>		32	40	54	58	68	78
	d <sub>3</sub>		18x2	20x5	25x5	30x5	35x5	40x5
	L <sub>4</sub>		must be given in ordering					
	$l_{3max}$		1500	1500	1500	2000	2000	2000
	$l_4$		25	30	35	40	50	55
	$l_5$		distance between shaft ends					
	S		5	6	6	8	10	11
	n		4,5	5	6	8	8	9
	m <sub>min</sub>		27	31	35	44	44	57



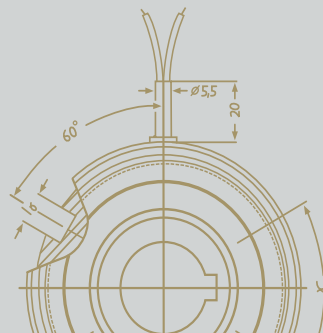
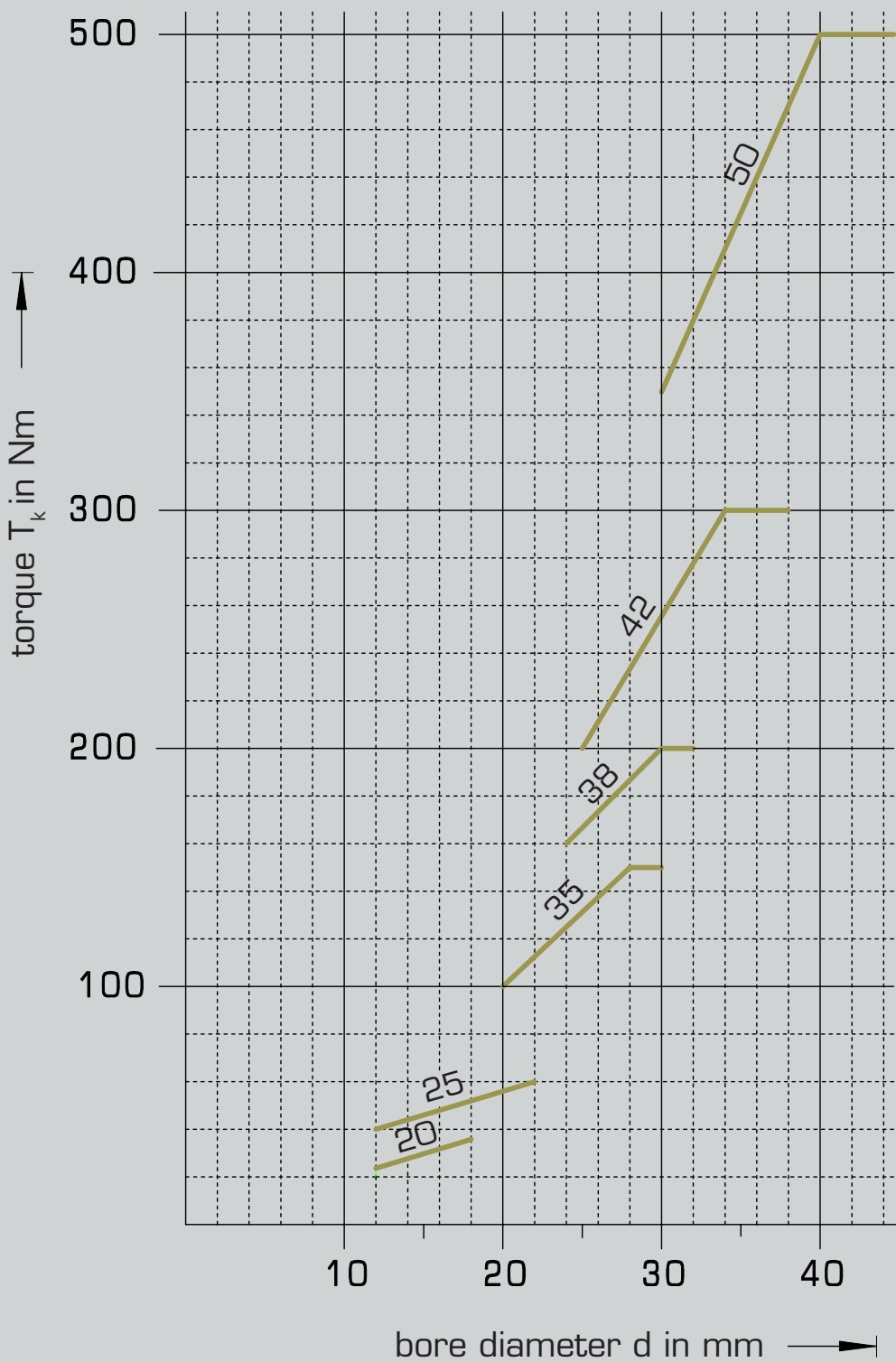




ServoFlex - Type 338

Clamping-hub connection option ...2

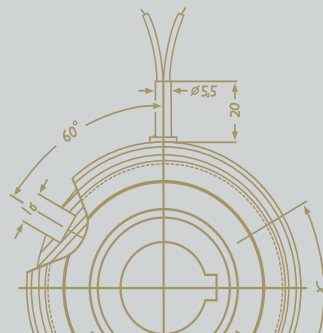
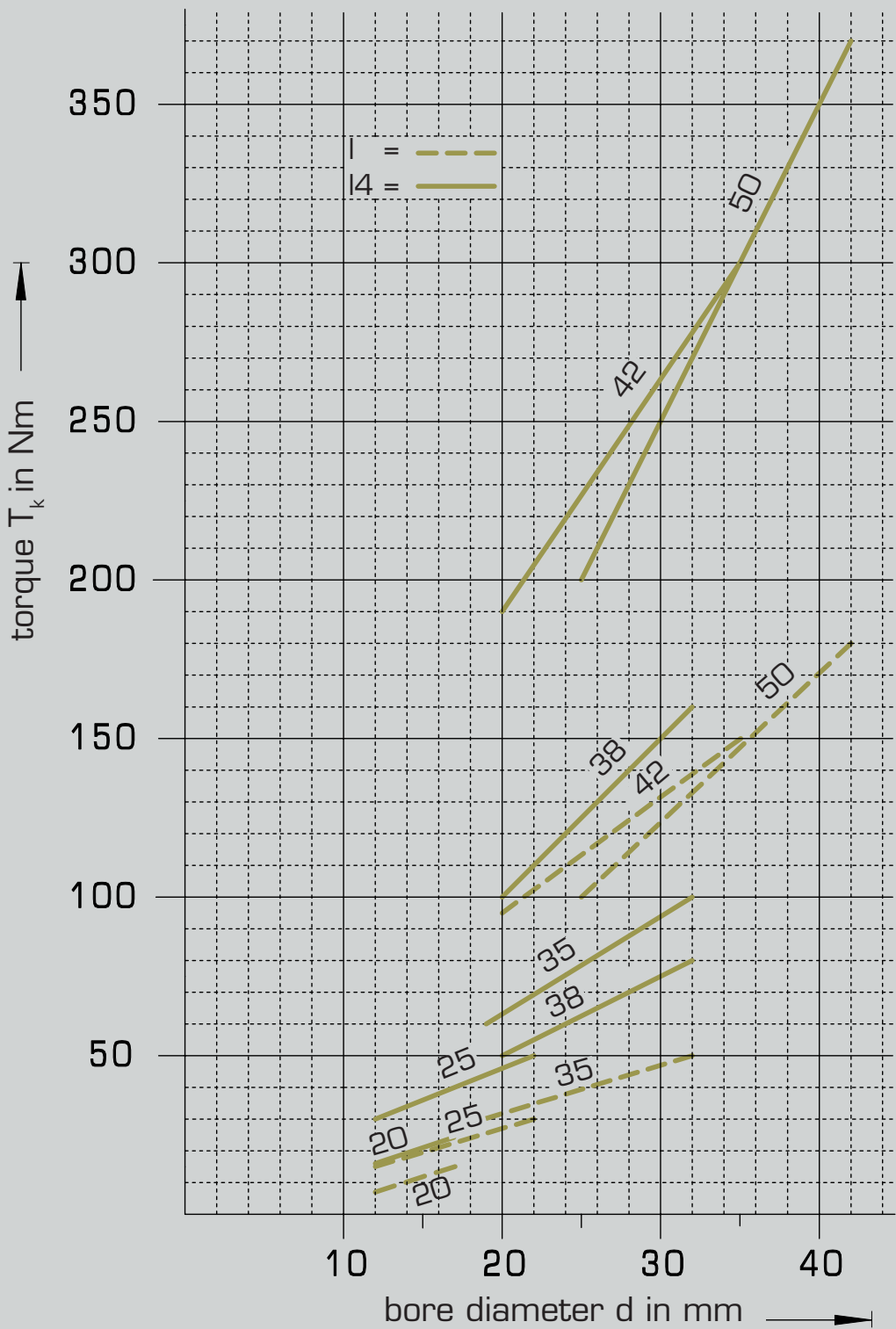
For design in stainless steel consult our technical department



ServoFlex - Type 338

Clamping-hub connection option ...4

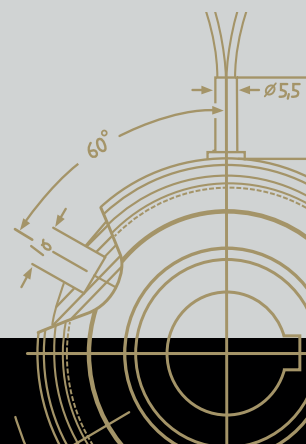
For design in stainless steel consult our technical department



## ServoFlex - Type 338

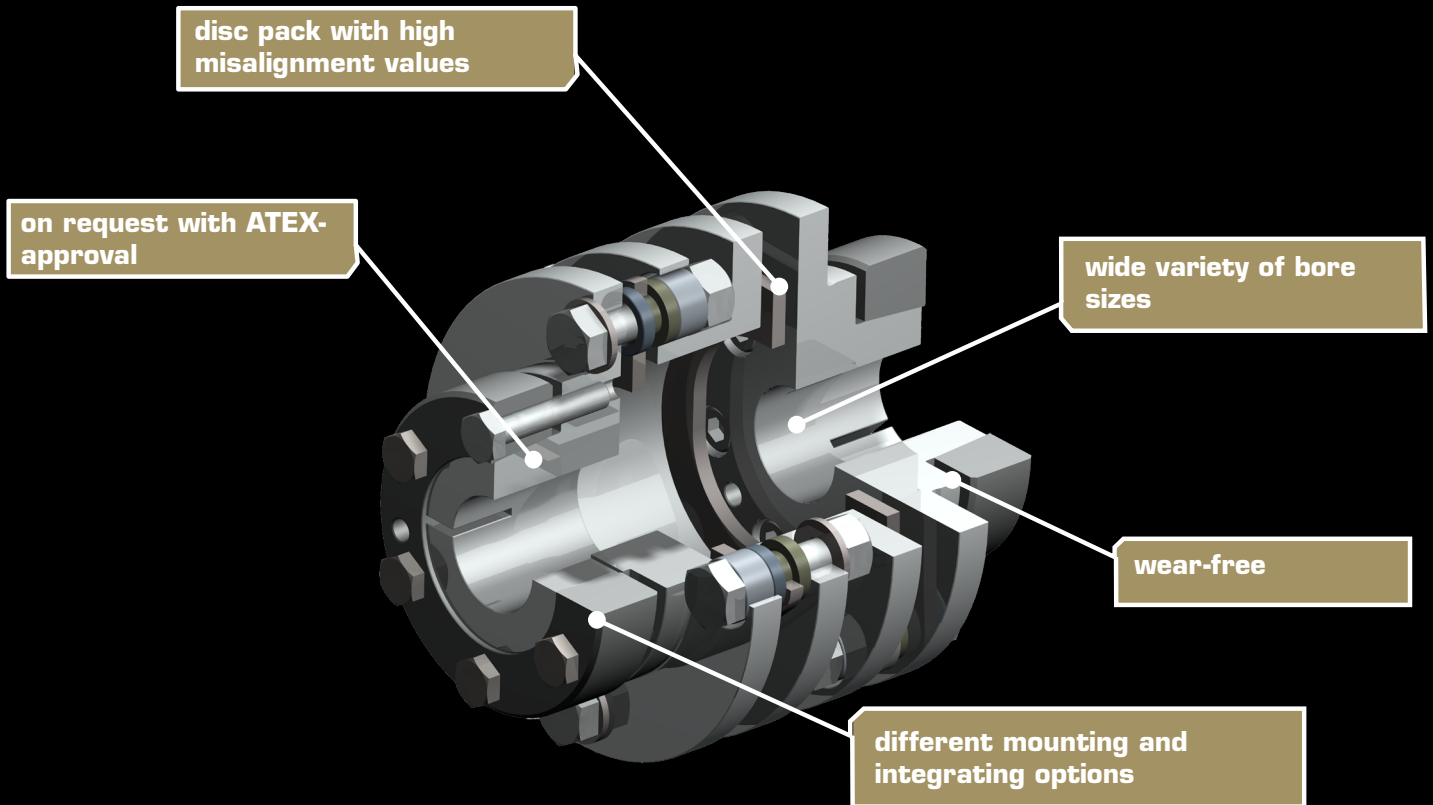
### Estimated operating factors for torsionally rigid shaft couplings

	Operating factor KB			shock factor $K_s$
	elektric motors turbines hydraulic motors	piston engines with more than 2 zylinders	piston engines with 1 or 2 zylinders	
<b>building construction machines</b>	2,1	2,5	3	4
<b>chemical industry</b>				
agitators (semi-liquid material)	1,7	2,1	2,6	3,5
agitators (liquid material)	1	1,4	1,7	2,5
centrifuges	1,35	1,75	2,2	2,5
pipeline pumps	1,7	2,1	2,6	4
<b>conveyors and lifts</b>				
goods lifts	1,7	2,1	2,6	4
passenger lifts	1,7	2,1	2,6	3,5
belt conveyors	1,7	2,1	2,6	3,5
<b>blowers, ventilators</b>	1,35	1,75	2,2	2,5
<b>generators, transformers</b>	1	1,4	1,7	3
<b>wood-plastic industry machinery</b>				
planing machines	1,7	2,1	2,6	4
woodworking machines	1	1,4	1,7	4
mixers	1,7	2,1	2,6	3
extruders	1,7	2,1	2,6	4
<b>cranes</b>	1,7	2,1	2,6	4
<b>metal working machines</b>				
presses	2,4	2,8	3,3	5
machine tools	1,7	2,1	2,6	3
<b>food industry machinery</b>				
kneading machines	1,7	2,1	2,6	3
mills	2,4	2,8	3,3	4,5
packaging machines	1	1,4	1,7	2
<b>paper machines</b>				
pulp grinders	2,4	2,8	3,3	4
shredder	2,4	2,8	3,3	4
presses, rolls	2,4	2,8	3,3	4
calenders	1,7	2,1	2,6	3,5
<b>pumps</b>				
piston pumps	2,4	2,8	3,3	4,5
centrifugal pumps	1,35	1,75	2,2	3
<b>stone and clay working machines</b>				
mills, breakers	2,4	2,8	3,3	6
rotary ovens	2,4	2,8	3,3	4
<b>textile machines</b>				
looms	1,7	2,1	2,6	3
winders	1,7	2,1	2,6	3
<b>compressors</b>				
pistons compressors	2,4	2,8	3,3	4
turbo compressors	1,7	2,1	2,6	2,5
<b>metal rolling mills</b>				
shears	2,4	2,8	3,3	5,5
plate-mill lines	2,4	2,8	3,3	5
cold rolling mills	2,4	2,8	3,3	5
rolling mill adjusters	1,7	2,1	2,6	4
winding machines	1,7	2,1	2,6	4
continuous casting plant	2,4	2,8	3,3	5
<b>laundries</b>	1,7	2,1	2,6	2,5



## ServoFlex - Type 338

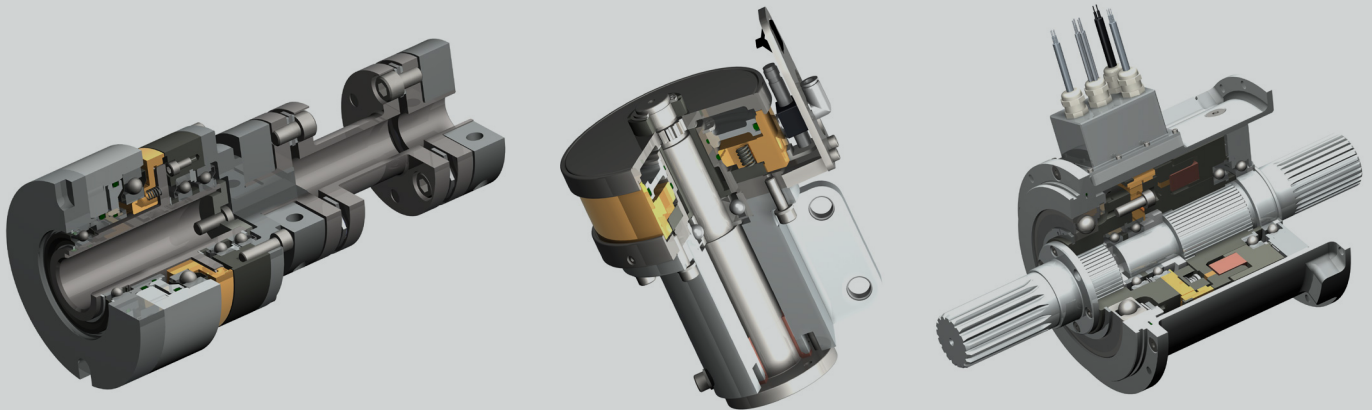
### At a glance



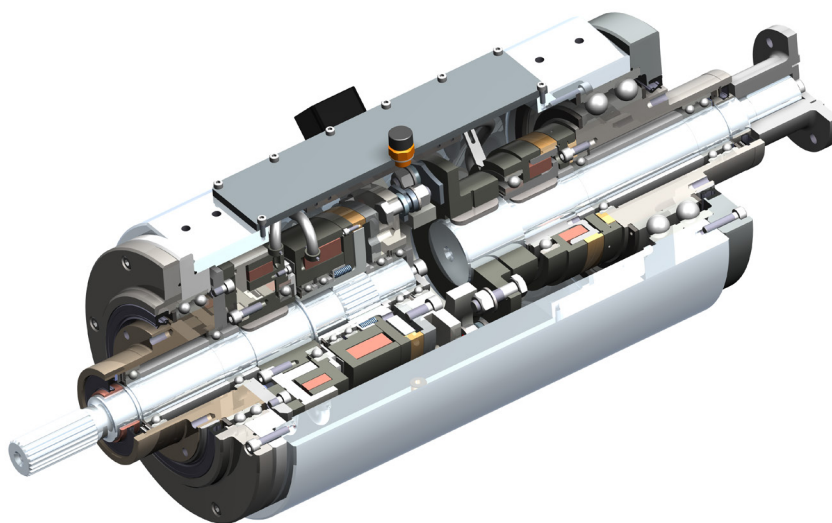
## System solutions

### You need more?

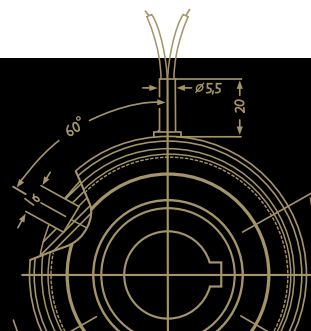
Mönninghoff clutches can be combined with a variety of many other power transmission elements. Such complex high-tech systems can solve any application-specific tasks and can fulfill any customer-specific wishes.



In many cases, a combination of different drive elements is needed to solve the applications particular problems and difficulties. Being not just supplier but technological partner to our customers, our extensive engineering is part of extraordinary and challenging power transmission projects.



**Our product is the know-how,  
with hardware as an added bonus.**



## Driven by excellence

### Why Mönninghoff

- intensive dialog with our customers' engineers
- decades of experience and competence
- deep understanding for all areas of mechanical engineering
- highly modern and flexible machine park
- enthusiasm for quality
- flexibility, inventiveness and communication skills of our employees
- commitment to Germany and Bochum as industrial location

### How to reach us

#### Sales

sales@moenninghoff.de  
+49 2327 3033-250



Helps you find a customer-specific power transmission solution for extraordinary circumstances.

#### Order Management

confirmation@moenninghoff.de  
+49 2327 3033-353



For the competent processing and smooth handling of your orders and delivery dates.

#### Service

service@moenninghoff.de  
+49 2327 3033-333



Feels committed to protect and preserve the high value of your machine and to secure its availability.

